

Case Case

00178624

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Case Detail

Case Number	00178624	Previous Case ID	11041095
Case Owner	<div><div></div>Michael Raymond</div>		
Account Name	<div><div></div>Certo Brothers - West Seneca, NY</div>		
Contact Name	<div><div></div>Ken Certo</div>		
Status	<div><div></div>Closed</div>		
Category	<div><div></div>Electrical</div>		
Priority	<div><div></div>3</div>		
Priority Description	<div><div></div>System Operational</div>		

Information

Subject	PLC: When they press the stop button on the cage door to robot #6 to stop robot
Description	PLC: When they press the stop button on the cage door to robot #6 to stop robot #6 Robot #1 stops.
Resolution	<div><div></div>Change coil adress in location 24:10 from 214:1/10 to 214:2/14</div>

System Information

Date/Time Opened	8/11/2006 5:57 AM	Date/Time Closed	8/25/2006 5:37 AM
Created By	Michael Raymond, 8/11/2006 5:57 AM	Last Modified By	Derek Camp, 1/22/2015 8:21 AM

Comments

Comments

Public Comment	Name	Date Time
I spoke with Ken and he reported the issue and discribed that when they press the request to enter cage #6 pushbutton Robot #1 would stop.	Michael	9/22/2014
	Raymond	10:08 AM
I reviewed the logic and spoke to the maintenance tech John Maddigan who detailed the issue further. I reviewed the logic and after some research found: N214:1/10 (Robot #1 Request to enter) used as Coil for: 23:1 with condition 63:2/2 (Robot Cell #1: Entry has been requested at 6CS) and 24:10 with condition 63:0/7 (Robot Cell #6: Entry Requested) I changed the coil for location 24:10 to N214:2/14 (Robot Cell #6: Request Entry From CC9)		
I contacted John and requested that he recreate the issue. John started both robots and press the entry request button on #6 and found #1 continued to run correctly.		

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